Series 2500 "OPTYMA-T"

General

With the introduction of the "T" configuration of solenoid valves with integrated pneumatic connections fitted directly on the sub base the 2500 series (called OPTYMA) is now richer than ever.

Many technical features make the new product interesting:

- Flow rate of 800 NI/min
- Tie rod system to hold the sub bases together
- All pneumatic connections (push-in) on the same side of the manifold
- Quick mounting of the valve to the base using just one screw
- Possibility to replace the valve without the need to disconnect the connections
- Possibility to use different pressures along the manifold (including vacuum)
- IP65 environmental protection
- Electrical connection directly integrated into the base, 32 electrical signals available (can be used to build up a manifold of 32
- monostable valves, 16 bistable valves or any combination within that limit).
- The electrical connection is made via 37 pin D-SUB connector.
- It is also available a 25-pole connector that is able to manage a maximum number of 22 electrical signals.

Possibility to integrate with Field Bus modules CANopen®, PROFIBUS DP, DeviceNet, EtherNet/IP, PROFINET IO RT/IRT, EtherCAT®,

Powerlink and Modbus/TCP.

Possibility to connect input modules, even on the base that does not have the Field Bus module. Large use of technopolymer material reduces the overall weight of the manifold.

"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power-Directional control valves-Measurement of shifting time"

Main characteristics

Integrated and optimized electrical connection system.

IP65 protection degree.

Only one 19mm size

Electrical line connections on one side

Monostable and bistable solenoid valves with the same size dimensions.

Easy and fast manifold assembly - tie rod system to hold the sub bases together

Quick coupling connections directly integrated in sub base Easy and fast manifold assembling.

Construction characteristics

Padu	Technonolymer
Воау	lecnnopolymer
Operators	Technopolymer
Spacers	NBR
Spacer	Technopolymer
Spools	Nickel - plated steel / Technopolymer
Springs	AISI 302 stainless steel
Pistons	Technopolymer
Piston seals	NBR

Functions

SV 5/2 MONOSTABLE SOLENOID-SPRING SV 5/2 MONOSTABLE SOLENOID-DIFFERENTIAL SV 5/2 BISTABLE SOLENOID-SOLENOID SV 5/3 C.C. SOLENOID-SOLENOID SV 2x3/2 N.C.-N.C. (=5/3 O.C.) SOLENOID-SOLENOID SV 2x3/2 N.O.-N.O. (=5/3 P.C.) SOLENOID-SOLENOID SV 2x3/2 N.C.-N.O. SOLENOID-SOLENOID

Technical characteristics

Voltage	24VDC \pm 10% PNP (NPN and AC on request)
Pilot consumption	1,3 Watt
Pilot working pressure (12-14)	From 3 to 7 bar max.
Valve working pressure [1]	from vacuum up to 10 bar
Operating temperature	-5°C +50°C
Protection degree	IP65
Life (standard operating conditions)	5000000
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous









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Solenoid-Solenoid 5/3

2541.53.31.35. Coding:

Operational characteristics			VOLTAGE
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous		02 = 24 VDC PNP
Norking pressure (bar)	From vacuum to 10		12 = 24 VDC NPN
Pressure range (bar)	3÷7		05 = 24 VAC
Temperature °C	-5 ÷ +50		ght 132 g
Flow rate at 6 bar with $\Delta p=1$ (NI/min)	600	SHO	RT FUNCTION CODE "E"
Responce time according to ISO 12238, activation time (ms)	15		
Responce time according to ISO 12238, deactivation time (ms)	20		
Shifting time of pneumatic directional control valves or moving parts, logic c	levices were measured in accordance to ISO 12238:2001		
	143.7	Ŧ	







Coding:

2541.62. . 35.

Solenoid-Solenoid 2x3/2

Operatio	onal characteristics		
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous		
Working pressure (bar)	From vacuum to 10		
Pressure range (bar)	3 ÷ 7		-
Temperature °C	-5 ÷ +50		E
Flow rate at 6 bar with $\Delta p=1$ (NI/min)	700		
Responce time according to ISO 12238, activation time (ms)	15		
Responce time according to ISO 12238, deactivation time (ms)	25		
Shifting time of pneumatic directional control valves or moving parts. Jogic devices were measured in accordance to ISO 12238:2001			_

	FUNCTION
	44 = NC-NC (5/3 Open centres)
	55 = NO-NO (5/3 Pressured
~	centres)
G	45 = NC-NO (normally
	closed-normally open)
	54 = NO-NC (normally
	open-normally closed)
	VOLTAGE
	02 = 24 VDC PNP
\mathbf{v}	12 = 24 VDC NPN
	05 = 24 VAC

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"Example: If inlet pressure is set at 5bar then pilot pressure must be at least Pp=2,5+(0.2*5)=3,5bar"



Connectors 25 poles

Right Endplates Operational characteristics Fluid Filtered air. N Working pressure (bar) Filtered air. N Temperature °C C



Filtered air. No lubrication needed, if applied it shall be continuous

From vacuum to 10

-5 ÷ +50

Coding: 2540.03.

SOLENOID PILOTS EXHAUST

25P =

Weight 274 g

00 = Electrical connection

Conduit 82/84=DO NOT PRESSURIZE,

Θ

2540.**V**.O Left Endplates Codina: **Operational characteristics** VERSION Filtered air. No lubrication needed, if applied it shall be continuous V 02 = External feeding Fluid Working pressure (bar) From vacuum to 10 12 = Self-feeding Pressure range (bar) 3 ÷ 7 ELECTRICAL CONNECTION Temperature °C -5 ÷ +50 37P







Weight 300 g

2540.02. Left Endplates-External feeding base: 12/14 divided from conduct 1



2540.12.



Weight 300 g

Left Endplates - Self-feeding Base: 12/14 connected with conduct 1



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Weight 53,5 g



Modular base



Operational characteristics			WORKING
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous	1	1 = G1/8'
Working pressure (bar)	From vacuum to 10	0	4 = Cartr
Temperature °C	-5 ÷ +50	11	6 = Quicl
		1	8 = Quicl

	WORKING PORTS SIZE
	1 = G1/8" female straight cartridge
Θ	4 = CartridgeØ4
-	6 = Quick fitting tube Ø6
	8 = Quick fitting tube Ø8
	VERSION
V	M = for Monostable SV
	B = for Bistable SV



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2540.10

	Weight 96,5 g
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Intermediate Inlet/Exhaust module		Coding:	2
Operati	onal characteristics		
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous		
Working pressure (bar)	From vacuum to 10		
Temperature °C	-5 ÷ +50		





Weight 115 g SHORT FUNCTION CODE "W"







Set with single tie-rod (max. 32 Solenoid valves)





Set with tie-rod, more extension adding a valve





General :

Each Optyma-T manifold lets to manage 32 command signals for the valves.

Optyma-T serial nodes (CANopen®, DeviceNet, PROFIBUS DP, EtherCAT®, PROFINET IO RT, EtherNet/IP and Powerlink) have a single pin for the power supply of the solenoid valves. So if you want to interrupt the power supply of one valve it is necessary to interrupt all the valves. The additional power supply module lets to interrupt at the same time the first 2 available command signals for the valves after the module itself. The additional power supply module is particularly useful also when you use control signals that block the valves. This application is effective both with serial management and multi-pole connection of the manifolds. This module is inserted directly into the Optyma-T solenoid valves manifold.

Ordering code

2540.10.2A

N:00

In particular this module is fitted with a M8 3 pins connector: +24V, not connected, GND.



ΈD

	PIN	DESCRIPTION
	1	+24 VDC
	4	NOT CONNECTED
3	3	GND

WORKING PRINCIPLE / SIMPLIFIED FUNCTIONAL DIAGRAM

This module uses an external power supply (+24VDC) to manage the solenoid valves.	_	4×	_
	INT	GND=	
	N 2		
	IN 3		
	IN 4		
	IN 5		
-	IN 6		0016
I he output signal from serial node	IN		OUT
is used as command signal: when	IN 32		OUT 32
If you want to cut off the power supply to a group of 2 valves it is sufficient to take away the +24VDC provided to the module			
supply to a group of 2 valves it is sufficient to take away the +24VDC provided to the module by the M8 connector.			

Please note: It is possible to use more modules to interrupt all the command signals,

simply by inserting them before the signals to interrupt and after the signals already interrupted.



EXAMPLE 1:

Manifold of 12 monostable valves on which you want to interrupt signals 7-8

Assembly:

- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,

- 6 monostable valves. Please note: the first 2 monostable of these are interruptible by the module, while the following 4 will work correctly managed directly by the corresponding command signals.



EXAMPLE 2:

Manifold of 12 monostable valves on which you want to interrupt signal 9

Assembly:

- 8 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 1 monostable valve (interruptible),
- 1 closing plate mounted on a monostable base,
- 3 monostable valves (work correctly managed directly by the corresponding command signals).



Please note: Each additional power supply module interrupts always 2 electrical signals.

- If you need to interrupt less than 2 signals you can:
- assemble the valves to interrupt in the last positions of the manifold, so you don't need to worry about the interrupted exceeding signals; - use a bistable base and mount a monostable valve (for each signal less than the 2 standard);
- use a monostable base and mount a closing plate (for each signal less than the 2 standard).

EXAMPLE 3:

Manifold of 7 monostable e 3 bistable valves on which you want to interrupt signals 2-3 and 8-9.

Assembly:

- 1 monostable valve (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves.

Please note: the first 2 monostable of these are interruptible by the module, while the following 4 will work correctly managed directly by the corresponding command signals.

- 1 additional power supply module,
- 3 bistable valves.

Please note: the first bistable of these valves is interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.





General :

Each Optyma-T manifold lets to manage 32 command signals for the valves. Optyma-T serial nodes (CANopen[®], DeviceNet, PROFIBUS DP, EtherCAT[®], PROFINET IO RT, EtherNet/IP and Powerlink) have a single pin for the power supply of the solenoid valves. So if you want to interrupt the power supply of one valve it is necessary to interrupt all the valves. The additional power supply module lets to interrupt at the same time the first 4 available command signals for the valves after the module itself. The additional power supply module is particularly useful also when you use control signals that block the valves. This application is effective both with serial management and multi-pole connection of the manifolds. This module is inserted directly into the Optyma-T solenoid valves manifold.

Ordering code

2540.10.4A



In particular this module is fitted with a M8 3 pins connector: +24V, not connected, GND.



GND

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WORKING PRINCIPLE / SIMPLIFIED FUNCTIONAL DIAGRAM

This module uses an external power supply (+24VDC) to manage the solenoid valves.		4× 1 3 GND	_
	IN 1		OUT 1
	IN 2		OUT 2
	IN 3		OUT 3
	IN 4		OUT 4
	IN 5		OUT 5
The output signal from serial node	IN 6		OUT 6
/ multi-pole connection	IN		OUT
is used as command signal: when it is high the +24VDC will be	IN 32		OUT 32
If you want to cut off the power			
supply to a group of 4 valves it is sufficient to take away the +24VDC provided to the module by the M8 connector.			

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simply by inserting them before the signals to interrupt and after the signals already interrupted.



Usage examples:

EXAMPLE 1:

Manifold of 12 monostable valves on which you want to interrupt signals 7-8-9-10

Assembly:

- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,

- 6 monostable valves. Please note: the first 4 monostable of these are interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.



EXAMPLE 2:

Manifold of 12 monostable valves on which you want to interrupt signals 7-8-9

Assembly:

- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 3 monostable valves (interruptible),
- 1 closing plate mounted on a monostable base,
- 3 monostable valves (work correctly managed directly by the corresponding command signals).



Please note: Each additional power supply module interrupts always 4 electrical signals.

- If you need to interrupt less than 4 signals you can:
- assemble the valves to interrupt in the last positions of the manifold, so you don't need to worry about the interrupted exceeding signals;
- use a bistable base and mount a monostable valve (for each signal less than the 4 standard);
- use a monostable base and mount a closing plate (for each signal less than the 4 standard).

EXAMPLE 3:

Manifold of 7 monostable e 3 bistable valves on which you want to interrupt signals 2-3-4-5 and 8-9-10-11.

Assembly:

- 1 monostable valve (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves.

Please note: the first 4 monostable of these are interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.

- 1 additional power supply module,
- 3 bistable valves.

Please note: the first 2 bistable of these valves are interruptible by the module, while the following will work correctly managed directly by the corresponding command signals.









The electrical connection is achieved by a 37 pin connector and can manage up to 32 solenoid pilots.

It is also possible use a 25 sub-D pin connector and, in this case, it is possible to manage a maximum of 22 outputs. The management and distribution of the electrical signals between each valve is obtained thanks to an electrical connector which receives the signals from the previous module, uses one, two or none depending on the type, and carries forward to the next module the remaining.

Bistable valves, 5/3 and 2x3/2 valves which have two solenoid pilots built in, use two signals; the first is directed to the pilot side 14 the second to the pilot side 12. Modular bases can be fitted with two type of electrical connector: the monostable version uses only one signal (connected to the pilot side 14) and carries forward the remaining, the bistable version which always uses two signals.

This solution allows the modification of the manifold (replacement of monostable valves without bistable for example) without having to reset the PLC output layout.

On other hand this solution limits the maximum number of valves to 16 when it is used a 37 pin connector or 11 when it is used a 25 pin connector.

Intermediate supply/exhaust module uses an electrical connector directly forwarding signals to the next one without any kind of modification.

This allows the use of intermediate modules in any position of the manifold.

All the electrical signals that have not been used on the manifold can be used placing at the end of the manifold the end plate complete with the 25 sub-D female connector.

The number of available signals depends of the connector used to the type of the left end plate and by the total signals used along the manifold:

37 pin connector nr of output = 32 - (total of used signals)nr of output = 22 - (total of used signals)25 pin connector

Following we show some examples of possible combination and the relative pin assignment.





37 PIN Connector correspondence for valves assembled on mixed bases



1	PIN	1	=	PILOT	14	sv	POS.	1
1	PIN	2	=	PILOT	12	SV	POS.	1
1	PIN	3	=	PILOT	14	SV	POS.	2
1	PIN	4	=	PILOT	14	SV	POS.	3
1	PIN	5	=	PILOT	14	SV	POS.	4
1	PIN	6	=	PILOT	12	SV	POS.	4
	PIN	7	=	PILOT	14	SV	POS.	5
1	PIN	8	=	PILOT	14	SV	POS.	7
	PIN	9	=	PILOT	14	SV	POS.	8
	PIN	10	=	PILOT	14	SV	POS.	9
	PIN	11	=	PILOT	14	SV	POS.	10
	PIN	12	=	PILOT	14	SV	POS.	11
	PIN	13	=	PILOT	12	SV	POS.	11
	PIN	14	=	PILOT	14	SV	POS.	12
	PIN	15	=	PILOT	12	SV	POS.	12

37 PIN Connector correspondence for manifold mounted on bases for bistable valves

	1 2	3 (4)	5	7 8	9 ₁₀		12	13 14	15 16	17 18	19 20	9 ₂		
3		No. of the second secon				and a second	THE STATE							
1					1									
E l'													1	h
		•	•	••	•		•	•	•	•				
L874-2						0			•				L	ť
an and a second	and	A STATE	A A A A A A A A A A A A A A A A A A A			ě		A DE LA		L T	建 定情	C Well	ANY DO FRAME	6
-						õ								
		Ш.	ш					Ш		Щ	Ш		-	/
POS.	1	2	3	4	5	6	7	8	9	10	11	12		

PIN 1	_	PILOT 14 S POS 1
PIN 2	=	PILOT 12 SV POS.1
PIN 3	=	PILOT 14 SV POS.2
PIN 4	=	NOT CONNECTED
PIN 5	=	PILOT 14 SV POS.3
PIN 6	=	NOT CONNECTED
PIN 7	=	PILOT 14 SV POS.4
PIN 8	=	PILOT 12 SV POS.4
PIN 9	=	PILOT 14 SV POS.5
PIN 10	=	NOT CONNECTED
PIN 11	=	PILOT 14 SV POS.7
PIN 12	=	NOT CONNECTED
PIN 13	=	PILOT 14 SV POS.8
PIN 14	=	NOT CONNECTED
PIN 15	=	PILOT 14 SV POS.9
PIN 16	=	NOT CONNECTED
PIN 17	=	PILOT 14 SV POS.10
PIN 18	=	NOT CONNECTED
PIN 19	=	PILOT 14 SV POS.11
PIN 20	=	PILOT 12 SV POS.11
PIN 21	=	PILOT 14 SV POS.12
PIN 22	=	PILOT 12 SV PUS.12

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21 22

37 PIN Connector correspondence for manifold for 32 position manifold with monostable valves on base

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General :

Using the 2540.03.25P output terminal it is possible to make any electrical signals not used by valves available on a 25 sub-D female connector at the right end of the manifold. It is possible to then join a multi-core cable to link to the next manifold, or connect directly to one or two I/O modules.

The I/O modules can accept input or output signals, depending upon what is connected.

Please note: If the manifold is connected by a multi-core connection, each connection can be used as either an input or an output, while if the manifold is connected to a serial node the connections can only be used as an output.

It is possible to connect the manifold to up to two I/O modules.

Each I/O module includes 8 diagnostic LEDs which indicate the presence of an Input / Output signal for each connector.

Please note: For an LED to function, a signal of at least +15VDC must be present on pin 4 of the connector. If this signal is lower, the LED will not light, this does not compromise the normal Input/Output function of the unit.

Overall dimensions and I/O layout :



Ordering code

2540.08T







PIN	DESCRIPTION
1	+24 VDC
4	INPUT/OUTPUT
3	GND

Input features:

Each connection can accept either two wire (switches, magnetic switches, pressure switches, etc.) or three wire connections (photocells, electronic end of stroke sensors, etc.) If +24VDC is required on at Pin 1 of each connector, it is possible to provide this via the through-line pin of the multi-pole connector.

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I.E : Pin 25 of the 25 pin multi-pole connector (code 2540.02.25P or 2540.12.25P)

> General characteristics

Pin 36-37 of the 37 pin multi-pole connector (code 2540.02.37P or 2540.12.37P)

Output features:



Attention: The output connections are not protected against short-circuit. Please pay attention when wiring (avoid Pin 4 being connected to Pin 3 or Pin 1).

	Model	2540.08T					
	Case	Reinforced technopolymer					
	I/O Connector	M8 connector 3 poles female (IEC 60947-5-2)					
	PIN 1 voltage	By the user					
	(connector used as Input)						
	PIN 4 voltage diagnosis	Green Led					
	Node consumption (Outlets excluded)	7mA per each LED with 24 VDC signal					
	Outlets voltage	+23,3 VDC (serial) /by the user (multipolar)					
	Input voltage	Depend by the using					
	Maximum outlet current	100 mA (serial) / 400 mA (multipolar)					
	Maximum Input/Output	8 per module					
	Multiconnector max. Current	100 mA					
	Connections to manifold	Direct connection to 25 poles connector					
	Maximum n. of moduls	2					
	Protection degree	IP65 when assembled					
	Ambient temperature	from -0° to +50° C					







AIR DISTRIBUTION



Please note: Optyma 32-T solenoid valve manifolds manage up to 32 signals. If the manifold uses more than 24 signals the I/O module will manage only the remainder. Connections that are not managing useful signals will remain unconnected.



B) Control via fieldbus:

With this kind of control the I/O module can only be used as an output. Pin 1 of each connector is not connected. The output voltage will be 0.7V lower than that applied to Pin 4 of the connector.

The maximum output current for each output is 100mA. The correspondence between control byte and each single output depends on how many electrical signals are used by the manifold and by the relative position of the I/O module.









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Solenoid valves manifold Series 2500 "OPTYMA-T"







Manifold Layout configuration



NOTE:

While configuring the manifold always be careful that the maximum number of electrical signals available is 32.

The use of monostable valve mounted on a base type 2 (2 electrical signals occupied) causes the loss of one electric signal. In this case the monostable valve can be replaced by a bistable valve. The diaphragms plugs are used to intercept the conduits 1,3 & 5 of the base. If it is necessary to interrupt more than one conduit in the same time then put in line the letters which identifies the position (for exemple : regarding the 3 & 5 conduits, put the Y & Z letters).

Should one or more conduits be cut more than one time it is necessary to add the relevant intermediate Supply/Exhaust module.

ACCESSORIES

J2	=	Power supply	Ζ	=	Diaphragm plug
		2 positions module			on pipe 5
J4	=	Power supply	XY	=	Diaphragm plug
		4 positions module			on pipe 1 & 3
V	=	Intermediate supply	ΖX	=	Diaphragm plug
		& exhaust module			on pipe 5 & 1
[=	Diaphragm plug	ΖY	=	Diaphragm plug
		on pipe 1			on pipe 5 & 3
,	=	Diaphragm plug	ZXY	′ =	Diaphragm plug
		on pipe 3			on pipe 5, 1 & 3

Series 2500 OPTYMA-T solenoid valve manifolds managed by multipoint connection are "well tried components"

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X

Y

Ψ	Well-tried component	 The product is a well-tried product for a safety-related application according to ISO 13849-1. The relevant basic and well-tried safety principles according
$B_{_{10d}}$	50.000.000	ISO 13849-2 for this product are fulfilled. - The suitability of the product for a precise application must be verified and confirmed by the user.